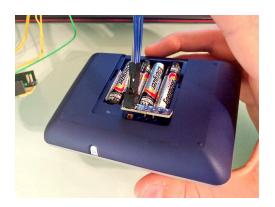
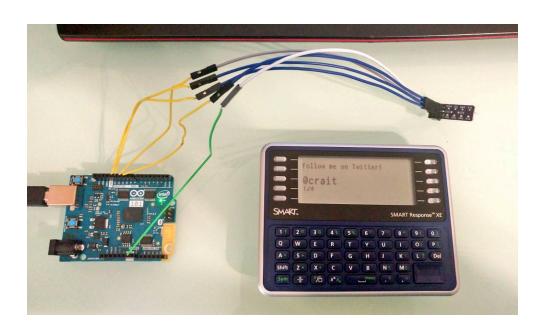
### **SmartResponse XE to Arduboy Project**

Parts List for Pogo-to-ICSP header adapter (<a href="https://github.com/securelyfitz/smartresponse">https://github.com/securelyfitz/smartresponse</a>):

- PCB from Osh Park: <a href="https://oshpark.com/shared">https://oshpark.com/shared</a> projects/1FKeJ3AI
- P50 pogo pins: <a href="https://www.ebay.ca/itm/100x-P50-B1-Dia-0-68mm-Length-16mm-75g-Spring-Pressure-Test-Probe-Pogo-Pin-F-Ch/392189237143?ssPageName=STRK%3AMEBIDX%3AIT&\_trksid=p2057872.m2749.l2649">https://www.ebay.ca/itm/100x-P50-B1-Dia-0-68mm-Length-16mm-75g-Spring-Pressure-Test-Probe-Pogo-Pin-F-Ch/392189237143?ssPageName=STRK%3AMEBIDX%3AIT&\_trksid=p2057872.m2749.l2649</a>
- ICSP 2x3 smt pins: Amphenol 54202-G08-03 or similar
   or: ICSP 2x3 smt socket: Harwin M20-7870346 or similar
   <a href="https://www.ebay.ca/itm/10pcs-1-27mm-Pitch-2x3-Pin-6-Pin-Female-Double-Row-SMT-S">https://www.ebay.ca/itm/10pcs-1-27mm-Pitch-2x3-Pin-6-Pin-Female-Double-Row-SMT-S</a>
   <a href="h







### **Important Links**

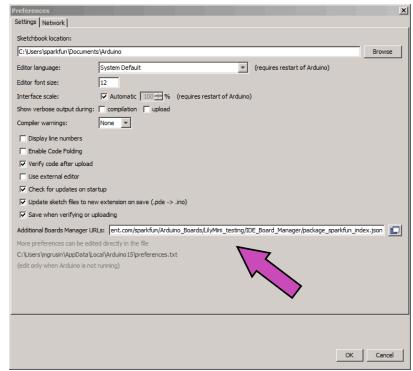
https://www.hackster.io/news/classroom-tool-converted-into-an-arduboy-df7908d9ee8c https://community.arduboy.com/t/smart-response-xe-re-purposed-into-arduboy/6094/411

### Links from Joe Fitz

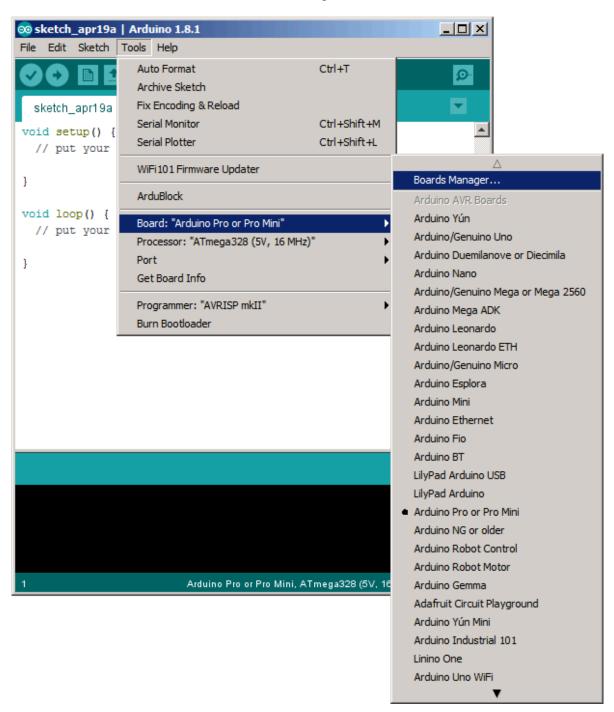
https://github.com/pdxbadgers/5ohBEE-2019 https://github.com/pdxbadgers/ATmega128RFA1\_Dev

### Setting up the Board

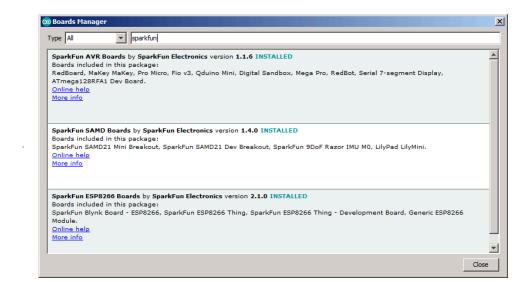
- 1. If using Linux you need to adjust the Udev rules to give access to the programmer and tell who the owner & permissions of the device will be (skip if using Windows or Arduino-as-isp).
  - udev rules: copy helpers/99-USBasp.rules to /etc/udev/rules.d/ (this assumes you are using the USBasp programmer, update your IDE accordingly)
- We need to Add the board to Arduino IDE (<a href="https://github.com/sparkfun/arduino\_boards">https://github.com/sparkfun/arduino\_boards</a>)
  - a. Open Arduino IDE, go to File -> Preferences
  - b. Add this link to the Additional Board Manager URLs:
  - c. <a href="https://raw.githubusercontent.com/sparkfun/Arduino\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Boards/master/IDE\_Board\_Board\_Boards/master/IDE\_Board\_Bo



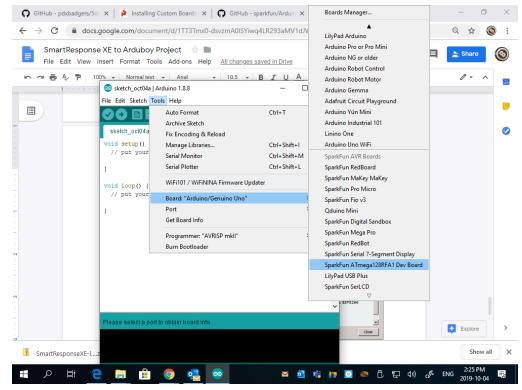
d. Go to Tools -> Board -> Boards Manager



e. If you type "sparkfun" (without quotes) into the "filter your search" field, you will see options to install SparkFun's Apollo3, AVR, and ESP board files. Click in the Sparkfun AVR box, and click the "Install" button that appears. Once installed, the boards will appear at the bottom of the board list.



 f. Go to Tools -> Boards Manager -> select "ATmega128RFA1 Dev Board" (under "Sparkfun AVR Boards")



- 3. Install dependencies: In Arduino IDE
  - a. Go to <a href="https://github.com/pdxbadgers/5ohBEE-2019">https://github.com/pdxbadgers/5ohBEE-2019</a> and download the SmartResponseXE-lib.zip
  - b. Select "Sketch" -> "Include Library" -> "Add .ZIP Library..." to add helpers/SmartResponseXE-lib.zip to the project

4.

5.

Downloaded 5ohBee.tar.gz from <a href="https://github.com/pdxbadgers/5ohBEE-2019">https://github.com/pdxbadgers/5ohBEE-2019</a> Install WinZip to open .gz format.

From the readme in the 5ohBee.tar.gz file:

# Arduino Board definitions for the ATmega128RFA1 Development Board

The \_sparkfun\_ folder should be added to a \*hardware\* directory within your Arduino sketchbook. Normally the sketchbook will install to your documents/Arduino folder. If a \*hardware\* folder isn't already there, make it.

This directory contains a \*boards.txt\* file which defines the ATmega128RFA1 Dev Board, and adds a selectable option under the \*Tools > Board\* menu. When you open the Arduino ID (close and reopen if it's already open), this option should be added to the menu.

### Find out which COM port to use

- go to device manager (WINKey + X), select Device manager and unfold ports (COM & LPT)
- connect Arduino Uno to PC and watch which COM port is added. This COM port
  must be selected in the Arduino IDE (and spacified on command line)

  Note: If there is no port added under ports but a device with an exclamation mark is
  added. Drivers need to be installed.

*Tip:* if you want to use a fixed COM port number like COM4, you can change the port number in device manager by right clicking the COM port > properties > port settings tab > advanced > at the bottom choose the port from the drop down menu and click OK twice.

## Make an ISP programmer from the Arduino Uno

- start Arduino IDE from the file menu, select examples > ArduinoISP > ArduinoISP and move to the new window.
- From tools menu select Arduino Uno/Genuino board (if not already selected)
- From the tools menu, Select the COM port and click the upload button (or press CTRL + U)
- Connect Arduino Uno to Smart Response XE using the following wiring:

```
Arduino Uno - Smart Response SE

Pin 10 - RST

pin 11 - MOSI

pin 12 - MISO

pin 13 - SCK

GND - GND

3.3V - VCC (only connect if the Smart response SE has no batteries.)
```

Smart Response SE programming pinout

# clearing lockbits and setting default fuses

The commandline tool avrdude is included with Arduino IDE and will be used to clear the lockbits and set the fuses.

- browse to the Arduino(installation)folder and browse into subfolder hardware\tools\avr
- rightclick the bin subfolder with shift pressed and click open command prompt here or open powershell here (Win10 default)
- for powershell: type cmd and press enter
- copy and paste the following line and press enter (Note: change COM4 to the correct port if it's not COM4)

```
avrdude -C..\etc\avrdude.conf -pm128rfa1 -cstk500v1 -PCOM4 -b19200 -e -Ulfuse:w:0xEE:m -Uhfuse:w:0x93:m -Uefuse:w:0xFC:m
```

This will erase the chip, reset the lock bits and sets the correct fuses for bootloader-less usage.

## Uploading a hexfile using AVRdude

here's the command to flash a hex file. Just repace <hexfile> with the fullpath to the hex file to flash:

```
avrdude -C..\etc\avrdude.conf -pm128rfa1 -cstk500v1 -PCOM4 -b19200 -e -Ulfuse:w:0xEE:m -Uhfuse:w:0x93:m -Uefuse:w:0xFC:m
```

Here's a sample hO access with simplified pin numbering (e.g.exfile for testing. It's Jetpac using an experimental interleaved display